

barebox – An introduction

Sascha Hauer <s.hauer@pengutronix.de>
Wolfram Sang <w.sang@pengutronix.de>
(ヴォルフラム ザング)



CELF Japan Technical Jamboree 32
Tokyo, 2010-03-05



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

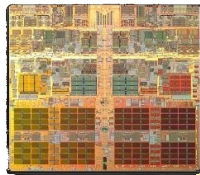
Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



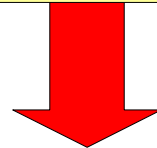
Bootloaders: What they do ...



Low Level Hardware Init

RAM, Flash, PLLs + Clocks, ...

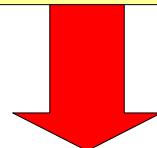
BIOS (PC)
Bootloader (SoC)



Fetch Kernel(s) from Boot Medium

NOR-Flash, NAND-Flash, SD, USB, SATA, Network...

BIOS (PC)
Bootloader
(SoC, PC)



Start Kernel

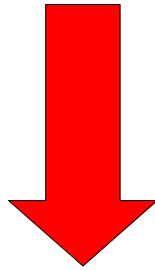
with kernel command line parameters

Bootloader
(SoC, PC)



Requirements for Production Systems

No interaction: power-on and boot
No delays by the bootloader!



The bootloader shall stay out of the way!

no selection screen
no nothing



Requirements: Development & Maintenance

Stop boot process in the bootloader:

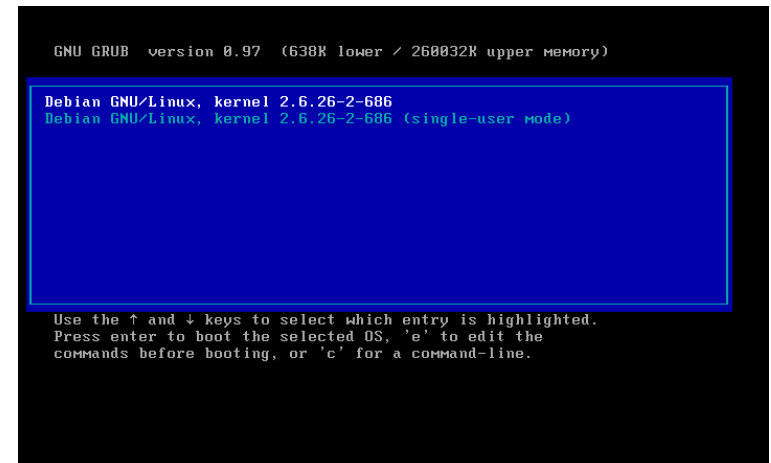
key press on keyboard (PC)
serial console key or
hardware button (embedded)

Choose between pre-existing **kernels**

Be able to edit kernel **location** - where to boot from
(flash partition, disk partition, tftp location, ...)

Change kernel **command line**

Make changes **persistent**
(change - store - boot with new config)



```
GNU GRUB version 0.97 (638K lower / 268832K upper memory)
Debian GNU/Linux, kernel 2.6.26-2-686
Debian GNU/Linux, kernel 2.6.26-2-686 (single-user mode)

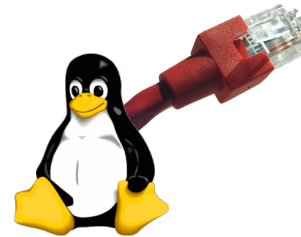
Use the ↑ and ↓ keys to select which entry is highlighted.
Press enter to boot the selected OS, 'e' to edit the
commands before booting, or 'c' for a command-line.
```



Common requirements for Embedded

Pre-loader for NAND

TFTP booting the kernel
(for quick development cycle)



Redundancy Boot
(start watchdog, boot,
boot other kernel on startup-failure)



Hardware testing environment:

have **register access** from a commandline
while kernel was not ported to a
new platform yet



have a **non-complex environment** for
hardware people to test prototypes



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



The barebox Project: Motivation for a fork

Pro U-Boot:

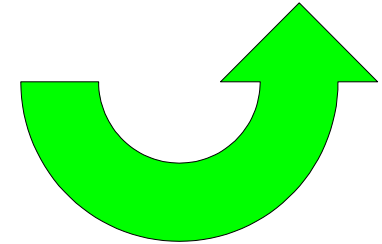
„Das U-Boot“ is a succesful bootloader
for SoC type Linux systems!

Multi platform design, runs on
ARM, MIPS, PowerPC, Blackfin etc.

Well **established**

High level of **configurability** (saveable environment)

“True” **Open Source** project
(no hidden development, public git + list)



The barebox Project: Motivation for a fork

Contra U-Boot:

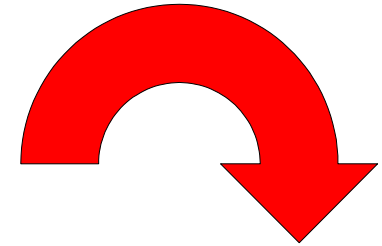
Operating U-Boot requires deep board **knowledge**

abuse of the **environment** for **scripting**

no clean driver model and multi instance concepts

Hard to configure: many macros have to be edited by hand to configure the features of U-Boot

“Must not break existing boards” policy
(makes it hard to change designs)



The barebox Project: Motivation for a fork

barebox was started as a technology study (named U-Boot-V2)

Idea: How can the U-Boot principle be improved when...

... we take **proven concepts** from Linux

... we **"think POSIX"**

...(we are **allowed to risk breaking** unmaintained platforms if really needed)

Can a bootloader feel more like Linux?



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



Design Decisions: A Bootloader for Kernel Hackers

Some design decisions we made for barebox:

more **abstraction**

(devices instead of direct memory access + special knowledge)

multi instance **driver model**

(no global variables, “**ethaddr**”, “**eth1addr**” etc. any more)

frameworks instead of multiple-drivers-with-(almost-)same-api

“**usual**” **commands**: rm, cp, ls, ...



Design Decisions: A Bootloader for Kernel Hackers

Some design decisions we made for barebox:

scripts are scripts, no “runnable environment variables”

use a **shell-like** environment

KBuild + Kconfig (easy configuration & build process)

models taken from the Linux kernel (clocks, ...)

kernel **coding style**

“**best of U-Boot and Linux**”



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



“Hello World” in barebox

Here is a typical startup from barebox:

```
barebox 2010.02.0-00065-g7aa3161 (Feb  4 2010 - 19:15:42)

Board: Phytex phyCard-i.MX27
NAND device: Manufacturer ID: 0x20, Chip ID: 0x36 (ST Micro NAND 64MiB
1,8V 8-bit)
Malloc space: 0xa7a00000 -> 0xa7f00000 (size  5 MB)
Stack space  : 0xa79f8000 -> 0xa7a00000 (size 32 kB)
running /env/bin/init...

Hit any key to stop autoboot:  3

type update_kernel nand|nor [<imagenam>] to update kernel into flash
type update_root  nand|nor [<imagenam>] to update rootfs into flash

barebox:/
```

File System

During startup, a RAM filesystem is mounted to /

A device filesystem is mounted to /**dev**

The environment is copied to /**env**

At the prompt, the well known commands like 'ls', 'rm', 'cp' work the way we are used to:

```
barebox:/ ls  
.  
..      dev      env
```



Devices

Drivers can create device nodes under `/dev` which can be accessed like normal files:

```
barebox:/ ls /dev/  
zero      defaultenv  mem         nand0       ram0  
phy0      self_raw    self0       env_raw     env0
```



Accessing Devices

While `/dev/mem` is the default “file” for the memory commands, it can be changed:

```
barebox:/ md -w -s /dev/phy0
00000000: 1000 786d 0022 1613 01e1 45e1 0007 2001 ..mx".....E...
00000010: 0000 0000 0000 0000 0000 0000 0000 0000 .....
```

This displays the contents of `/dev/phy0` (-s) in 16 bit wordsize (-w)



Device Variables

Design criterium: "avoid magic variables"

Introduction of "device variables": `eth0.ipaddr`

Device variables can be displayed using the `devinfo` command:

```
barebox:/ devinfo eth0
base  : 0x00000000
size  : 0x00000000
driver: none

Parameters:
      ipaddr = 192.168.24.26
      ethaddr = 00:50:c2:a5:bb:87
      gateway = 192.168.1.1
      netmask = 255.255.0.0
      serverip = 192.168.23.2
```

The device variables can be used like any other variable:

```
barebox:/ eth0.serverip=192.168.23.123
barebox:/ echo $eth0.serverip
192.168.23.123
```



Partitioning

Device files can be partitioned to get a convenient access to flashes and to get a consistent partition layout between barebox and Linux:

```
barebox:/ addpart nor0 256k(barebox) ,128k(barebox-env) ,2M(kernel) , -  
      (rootfs)  
barebox:/ ls -l /dev/nor0*  
crw----- 31064064 /dev/nor0.rootfs  
crw----- 2097152  /dev/nor0.kernel  
crw----- 131072  /dev/nor0.barebox-env  
crw----- 262144  /dev/nor0.barebox  
crw----- 33554432 /dev/nor0
```

The partition description for the “addpart” command is the same as the Linux mtd layer uses for command line partitioning, so this string can be directly given to the Kernel



Getting the Kernel via TFTP

Most important networking commands:

dhcp (configure the network adapter)

tftp (transfer files via tftp, can write directly to flash)

```
barebox:/ erase /dev/nor0.kernel
barebox:/ dhcp
phy0: Link is up - 100/Full
BOOTP broadcast 1
DHCP client bound to address 192.168.24.26

barebox:/ tftp zImage-pca100 /dev/nor0.kernel
phy0: Link is up - 100/Full
TFTP from server 192.168.23.2; our IP address is 192.168.24.26
Filename 'zImage-pca100'.
Loading: #####
          #####
          #####
done
Bytes transferred = 1815016 (1bb1e8 hex)
```



Build System

Building should be familiar to kernel hackers:

```
# export ARCH=arm
# export CROSS_COMPILE=arm-linux-
# make pcm038_defconfig
# make menuconfig
# make
```



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



Sugar & Candies: Highlights

Minimal **porting effort**

Can be a **2nd stage** bootloader (e.g if first level is proprietary)

“One-image-**starts-everywhere**” (NAND, NOR, RAM...)

Highly **scalable** (modular)

Support for **MMU, USB** (host/device), **DFU, splashscreens**,...

GPL v2 (as the kernel)

integrated **shell & editor**

Binary size usually from 9KB to 150KB



Sandbox

barebox can be built as a normal **Linux binary**
(inspired by user mode linux)

Features:

Working on barebox **without** real **hardware**

Run under **gdb**

Networking using a **tap device**

To compile the sandbox: pass **ARCH=sandbox** while compiling



Showtime!

See barebox in action



barebox: Agenda

Bootloaders: What they do and why we (still) need them

The barebox Project: Motivation for a fork

Design Decisions: A Bootloader for Kernel Hackers

Flow of Execution: From Power-On to the Kernel

Sugar and Candies: Some Highlights

Summary & Discussion



Summary & Discussion

barebox wants to give you a **Linux feeling** inside a bootloader

- when working on the command-line
- when developing for it

So developers feel at home and can work **faster** making **less errors** (hopefully :)).

It aims for great **flexibility** to meet a number of use cases.

Alternative: boot with Linux (kexec)

initial porting effort?

penalties in boot time and storage consumption?

NAND pre-loader?



Links

Web Site for barebox:

<http://www.barebox.org/>

Source Code:

```
git clone git://git.pengutronix.de/git/barebox.git
```

Mailing List:

<http://lists.infradead.org/mailman/listinfo/barebox>

Questions? Ask me now or anytime later:

w.sang@pengutronix.de

