

# Software Updates with RAUC, the Yocto Project and OpenEmbedded

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- Services company specializing in Embedded Linux and Open Source Software
- Hardware/software build, design, development, and training services
- Based in San Jose, CA with an engineering presence worldwide
- <http://konsulko.com/>

# Agenda

- Introduction to software updates and RAUC
- RAUC practical example with Raspberry Pi 4
- Eclipse hawkBit
- Conclusions
- Q&A

# Common Embedded Linux Update Strategies



- A/B updates (dual redundant scheme)
- Delta updates
- Container-based updates
- Combined strategies

## ■ Combined Strategies

- Container technology has changed the way application developers interact with the cloud and some of the good practices are nowadays applied to the development workflow for embedded devices and IoT
- Containers make applications faster to deploy, easier to update and more secure through isolation
- Yocto/OE layer [meta-virtualization](#) provides support for building Xen, KVM, Libvirt, docker and associated packages necessary for constructing OE-based virtualized solutions
- There are use cases on powerful embedded devices where contains are combined with A/B updates of the base Linux distribution built with Yocto/OE

# Are there any RAUC open source alternatives?

- Mender
- SWUpdate
- Swupd
- UpdateHub
- Balena
- Snap
- OSTree
- Aktualizr
- Aktualizr-lite
- QtOTA
- Torizon
- FullMetalUpdate
- Rpm-ostree (used in Project Atomic)

- A lightweight update client that runs on an Embedded Linux device and reliably controls the procedure of updating the device with a new firmware revision
- Provides tool for the build system to create, inspect and modify update bundles
- Uses X.509 cryptography to sign update bundles
- Compatible with the Yocto Project and OpenEmbedded, PTXdist and Buildroot
- Created by Pengutronix in 2015



- RAUC - LGPLv2.1  
<https://github.com/rauc/rauc>
- meta-rauc - MIT  
<https://github.com/rauc/meta-rauc>
- rauc-hawkbite - LGPLv2.1  
<https://github.com/rauc/rauc-hawkbite>
- rauc-hawkbite-updater - LGPLv2.1  
<https://github.com/rauc/rauc-hawkbite-updater>



- Yocto/OpenEmbedded meta layer for RAUC
- Supports releases Gatesgarth, Dunfell, Zeus, Warrior, Thud, Sumo, Morty, Pyro and Krogoth
- Available under MIT license in GitHub: <https://github.com/rauc/meta-rauc>
- 22 contributors, the RAUC co-maintainer Enrico Jörns from Pengutronix is the leading contributor

# RAUC Integration Steps

- Select an appropriate bootloader
- Enable **SquashFS** in the Linux kernel configurations
- **ext4** root file system (RAUC does not have an ext2 / ext3 file type)
- Create specific partitions that matches the RAUC slots
- Configure Bootloader environment and create a script to switch RAUC slots
- Create a certificate and a keyring to RAUC's system.conf

# RAUC Example with Raspberry Pi 4

# RAUC Example with Raspberry Pi 4

- Download Poky, meta-openembedded and meta-raspberrypi:

```
git clone -b dunfell git://git.yoctoproject.org/poky poky-rpi-rauc
cd poky-rpi-rauc
git clone -b dunfell git://git.openembedded.org/meta-openembedded
git clone -b dunfell git://git.yoctoproject.org/meta-raspberrypi
```

- Download RAUC related layers:

```
git clone -b dunfell https://github.com/rauc/meta-rauc.git
git clone -b dunfell https://github.com/leon-anavi/meta-rauc-community.git
```

- Initialize the build environment:

```
source oe-init-build-env
```

# RAUC Example with Raspberry Pi 4

- Add layers:

```
bitbake-layers add-layer ../meta-openembedded/meta-oe/  
bitbake-layers add-layer ../meta-openembedded/meta-python/  
bitbake-layers add-layer ../meta-openembedded/meta-networking/  
bitbake-layers add-layer ../meta-openembedded/meta-multimedia/  
bitbake-layers add-layer ../meta-raspberrypi/  
bitbake-layers add-layer ../meta-rauc  
bitbake-layers add-layer ../meta-rauc-community/meta-rauc-raspberrypi/
```

# RAUC Example with Raspberry Pi 4

- Add to local.conf:

```
MACHINE = "raspberrypi4"  
DISTRO_FEATURES_append = " systemd"  
VIRTUAL-RUNTIME_init_manager = "systemd"  
DISTRO_FEATURES_BACKFILL_CONSIDERED = "sysvinit"  
VIRTUAL-RUNTIME_initscripts = ""  
IMAGE_INSTALL_append = " rauc"  
IMAGE_FSTYPES="tar.bz2 ext4 wic.bz2 wic.bmap"  
SDIMG_ROOTFS_TYPE="ext4"  
ENABLE_UART = "1"  
RPI_USE_U_BOOT = "1"  
PREFERRED_PROVIDER_virtual/bootloader = "u-boot"  
WKS_FILE = "sdimage-dual-raspberrypi.wks"
```

# RAUC Example with Raspberry Pi 4

- Build a minimal bootable image:

```
bitbake core-image-minimal
```

- Flash the image to a microSD card and boot it on Raspberry Pi 4:

```
sudo umount /dev/sdX*  
bzcat tmp/deploy/images/raspberrypi4/core-image-minimal-raspberrypi4.wic.bz2 | sudo dd of=/dev/sdX  
sync
```

- Attach USB to UART debug cable to Raspberry Pi 4, plug ethernet cable and the microSD card. Turn on Raspberry Pi 4. Verify that the system boots successfully.

# RAUC Update Bundle

- Add to conf/local.conf:

```
IMAGE_INSTALL_append = " nano"
```

- Build a RAUC bundle:

```
bitbake update-bundle
```



# Manual RAUC Update of Raspberry Pi 4

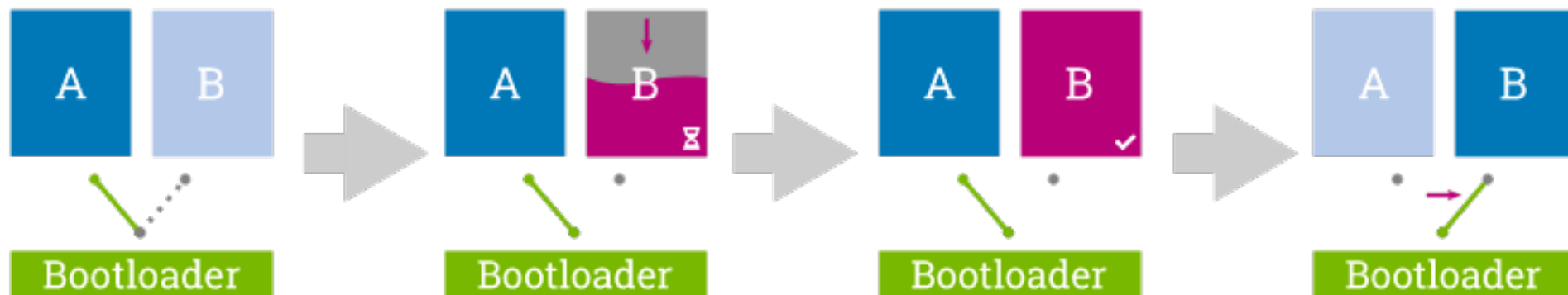
- On the build system:

```
cd tmp/deploy/images/raspberrypi4/  
python3 -m http.server
```

- On the embedded device, in this case Raspberry Pi 4:

```
wget http://example.com:8000/update-bundle-raspberrypi4.raucb -P /tmp  
rauc install /tmp/update-bundle-raspberrypi4.raucb  
reboot
```

# Manual RAUC Update of Raspberry Pi 4



# Check RAUC Status After Update

```
leon@leon-ThinkPad-T480s: ~  
raspberrypi4 login: root  
root@raspberrypi4:~# which nano  
/usr/bin/nano  
root@raspberrypi4:~# rauc status  
=== System Info ===  
Compatible: RaspberryPi4  
Variant:  
Booted from: rootfs.1 (B)  
  
=== Bootloader ===  
Activated: rootfs.1 (B)  
  
=== Slot States ===  
x [rootfs.1] (/dev/mmcblk0p3, ext4, booted)  
  bootname: B  
  mounted: /  
  boot status: good  
  
o [rootfs.0] (/dev/mmcblk0p2, ext4, inactive)  
  bootname: A  
  boot status: good  
  
root@raspberrypi4:~#
```

How Does It Work?

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# U-Boot Environment for RAUC

RAUC relies on the following U-Boot environment variables:

- **BOOT\_ORDER** - a space-separated list of boot targets in the order they should be tried
- **BOOT\_<bootname>\_LEFT** - contains the number of remaining boot attempts to perform for the respective slot

- For details:

<https://rauc.readthedocs.io/en/latest/integration.html#set-up-u-boot-environment-for-rauc>

# boot.cmd.in for RAUC & Raspberry Pi

```
fdt addr ${fdt_addr} && fdt get value bootargs /chosen bootargs
test -n "${BOOT_ORDER}" || setenv BOOT_ORDER "A B"
test -n "${BOOT_A_LEFT}" || setenv BOOT_A_LEFT 3
test -n "${BOOT_B_LEFT}" || setenv BOOT_B_LEFT 3
test -n "${BOOT_DEV}" || setenv BOOT_DEV "mmc 0:1"
setenv bootpart
setenv raucslot
for BOOT_SLOT in "${BOOT_ORDER}"; do
  if test "x${bootpart}" != "x"; then
    # skip remaining slots
  elif test "x${BOOT_SLOT}" = "xA"; then
    if test ${BOOT_A_LEFT} -gt 0; then
      setexpr BOOT_A_LEFT ${BOOT_A_LEFT} - 1
      echo "Found valid RAUC slot A"
      setenv bootpart "/dev/mmcblk0p2"
      setenv raucslot "A"
      setenv BOOT_DEV "mmc 0:2"
    fi
  elif test "x${BOOT_SLOT}" = "xB"; then
    if test ${BOOT_B_LEFT} -gt 0; then
      setexpr BOOT_B_LEFT ${BOOT_B_LEFT} - 1
      echo "Found valid RAUC slot B"
      setenv bootpart "/dev/mmcblk0p3"
      setenv raucslot "B"
      setenv BOOT_DEV "mmc 0:3"
    fi
  fi
done
```

```
if test -n "${bootpart}"; then
  setenv bootargs "${bootargs} root=${bootpart} rauc.slot=${raucslot}"
  saveenv
else
  echo "No valid RAUC slot found. Resetting tries to 3"
  setenv BOOT_A_LEFT 3
  setenv BOOT_B_LEFT 3
  saveenv
  reset
fi
fatload mmc 0:1 ${kernel_addr_r} @@KERNEL_IMAGETYPE@@
if test ! -e mmc 0:1 uboot.env; then saveenv; fi;
@@KERNEL_BOOTCMD@@ ${kernel_addr_r} - ${fdt_addr}
```

# SquashFS & Loopback Device Support

- To install RAUC bundles the kernel used on the embedded device must support both loop block devices and the SquashFS file system
- For Raspberry Pi in `linux-raspberrypi_%.bbappend`:

```
do_configure_append() {  
    kernel_configure_variable SQUASHFS y  
    kernel_configure_variable BLK_DEV_LOOP y  
    kernel_configure_variable SQUASHFS_FILE_CACHE y  
    kernel_configure_variable SQUASHFS_DECOMP_SINGLE y  
    kernel_configure_variable SQUASHFS_ZLIB y  
    kernel_configure_variable SQUASHFS_FRAGMENT_CACHE_SIZE 3  
}  
CMDLINE_remove = "root=/dev/mmcblk0p2"
```

# Generate RAUC Certificate

Use script `openssl-ca.sh` from `meta-rauc` to create a certificate and a key:

- The target RAUC package must use the generated keyring file
- RAUC bundle recipe must use the generated key and certificate
  
- For details:  
<https://github.com/rauc/meta-rauc/blob/master/scripts/README>



# RAUC Bundle Generator update-bundle.bb

```
DESCRIPTION = "RAUC bundle generator"
```

```
inherit bundle
```

```
RAUC_BUNDLE_COMPATIBLE = "RaspberryPi4"
```

```
RAUC_BUNDLE_VERSION = "v20200703"
```

```
RAUC_BUNDLE_DESCRIPTION = "RAUC Demo Bundle"
```

```
RAUC_BUNDLE_SLOTS = "rootfs"
```

```
RAUC_SLOT_rootfs = "core-image-minimal"
```

```
RAUC_SLOT_rootfs[fstype] = "ext4"
```

```
RAUC_KEY_FILE = "${THISDIR}/files/development-1.key.pem"
```

```
RAUC_CERT_FILE = "${THISDIR}/files/development-1.cert.pem"
```

One More Thing...

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# Eclipse hawkBit

- Domain independent back-end framework for rolling out software updates to constrained edge devices as well as more powerful controllers and gateways connected to IP based networking infrastructure
- Written in Java
- Available in GitHub under EPL-1.0 License
- Compatible with **RAUC** and **SWUpdate**
- <https://www.eclipse.org/hawkbit/>



# Eclipse hawkBit

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The screenshot displays the Eclipse hawkBit Software Provisioning interface, divided into two main sections: Deployment Management and Upload Management.

**Deployment Management:**

- Filters:** Simple Filter (NO TAG, Europe, Simulated).
- Targets:** A list of targets including dmfSimulated0 through dmfSimulated11. Target dmfSimulated0 is selected.
- Distributions:** A table showing Baseline 1 and Baseline 2.
- Action History For dmfSimulated0:** A table showing two actions: Baseline:2 (Mi Feb 8 07:12:43 M...) and Baseline:1 (Mi Feb 8 07:12:33 M...).
- Target Details for dmfSimulated0:** Controller id: dmfSimulated0, Last poll: Mi Feb 8 07:14:51 MEZ 2017, Address: amqp/simulator\_replyTo, Security token: quzAK41mltBeGQcOHW.
- Distribution set: Baseline:1:** Type: OS only, Required Migration Step: No.
- Summary:** Total Targets: 1000. Buttons: Drop here to delete, No actions.

**Upload Management:**

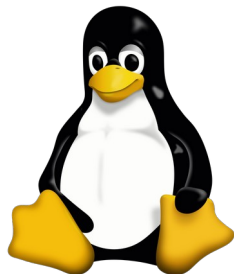
- Software Module:** A table showing two modules: A Firmware (Version 1) and A Firmware (Version 2).
- Artifact Details of A Firmware:1:** File name, Size(B), Last modified date, Action.
- Software Module: A Firmware:1:** Details, Description, Logs, Metadata. Vendor: Type: OS, Assignment type: Firmware (FW).
- Summary:** Buttons: Drop here to delete, No actions, Upload file, Process, Discard.

The interface includes a sidebar with navigation options: Deployment, Rollout, Target Filters, Distributions, Upload, and System Config. The hawkBit logo is visible in the top right of both sections.

# Conclusions

- RAUC is a secure, reliable, free and open source framework for A/B software updates of embedded Linux devices
- meta-rauc is the Yocto/OpenEmbedded layer providing RAUC
- Additional specific integration is required depending on the hardware and the BSP
- Recipe should create the RAUC update bundles
- Eclipse hawkBit is a domain independent back-end framework with web interface for managing update and it is compatible with RAUC

# Thank You!



## Useful links

- <https://rauc.io/>
- Getting Started with RAUC on Raspberry Pi, an article at konsulko.com  
<https://www.konsulko.com/getting-started-with-rauc-on-raspberry-pi-2/>
- Behind the Scenes of an Update Framework: RAUC, Enrico Jörns, ELCE 2019  
<https://www.youtube.com/watch?v=ZkumnNsWczM>
- Embedded Recipes 2019 - Remote update adventures with RAUC, Yocto and Barebox  
<https://www.youtube.com/watch?v=hS3Fjf7fuHM>
- Secure and Safe Updates for Your Embedded Device, Enrico Jörns, FOSDEM 2017  
[https://archive.fosdem.org/2017/schedule/event/secure\\_safe\\_embedded\\_updates/](https://archive.fosdem.org/2017/schedule/event/secure_safe_embedded_updates/)