

Creating Bluetooth[®]-based IoT Solutions with Zephyr[™] OS



Zephyr is a trademark of the Linux Foundation.



Bluetooth low energy technology

- Also known as BLE or Bluetooth Smart
- Introduced in 2010 with Bluetooth 4.0
- 2.4 GHz, slightly different radio modulation than Bluetooth Classic
- 100m range, 1Mbps bandwidth
- Years of battery life on a coin-cell battery
- Controllers come in single- & dual-mode variants
- Perfect for IoT use-cases



Zephyr OS Bluetooth Stack

- Bluetooth 4.2 compliant
- Almost complete low energy feature set
 - L2CAP Connection-oriented Channels
 - LE Secure Connection
- Bluetooth Classic (BR/EDR) on its way
- Host-controller separation through HCI
- Recently added controller implementation



Bluetooth host stack architecture

- GAP (Generic Access Profile)
 - Peripheral & Central
 - Observer & Broadcaster
- IPSP for IPv6 over Bluetooth LE
- Clean HCI driver abstraction
 - Standard physical transport drivers (e.g. UART)
 - Virtual driver for local Controller support
- Verified with multiple popular controllers
- Highly configurable
 - Features, buffer sizes/counts, etc.





Host stack runtime view





Network buffer integration

- Common network buffer API: net_buf
- Easy encoding & decoding
- Fragmentation
- (Near) zero-copy
- Compatible with kernel objects like FIFOs
- Cross-layer, e.g. to/from controller
- Cross-subsystem to/from IP stack



Configuring Bluetooth Host Features

- HCI driver
- Features
 - GAP/GATT roles
 - Security (pairing & signing)
- Define buffer sizes & counts
- Number of paired devices
- Number of connections (even 0)
- Debug options

Bluetooth support Arrow keys navigate the menu. <enter> selects submenus> (or empty submenus). Highlighted letters are hotkeys. Pressing <y> includes, <n> excludes, <m> modularizes features. Press <esc><esc> to exit, <? > for Help, for Search. Legend: [*] built-in []</esc></esc></m></n></y></enter>
<pre> Bluetooth support Bluetooth Stack Selection (HCI Stack)> *** HCI Stack Configurations *** [*] Bluetooth Low Energy (LE) support (NEW) (2) Number of HCI command buffers (NEW) (64) Maximum supported HCI command length (NEW) (68) Maximum supported HCI event length (NEW) (68) Maximum supported HCI event length (NEW) (5) Number of incoming ACL data buffers (NEW) (23) Maximum supported L2CAP MTU for incoming data (NEW) (1024) Size of the receiving fiber stack (NEW) (1024) Size of the receiving fiber stack (NEW) (23) Attribute Protocol (ATT) channel MTU (NEW) (23) Attribute Protocol (ATT) channel MTU (NEW) (0) Number of ATT prepare write buffers (NEW) (1) Number of ATT request buffers (NEW) (1) Security Manager Protocol support (NEW) (2) L 2CAP Dynamic Channel support (NEW) (3) Attri dynamic database support (NEW) (4) +(+)</pre>
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Creating a Bluetooth LE application

- Initialize the stack
 - bt_init()
- Register GATT service database
 - bt_gatt_register(services)
- Advertise and let others connect
 - bt_le_adv_start(parameters)
- Notify of value changes
 - bt_gatt_notify(parameters)
- Many samples available
 - samples/bluetooth/*



Development tools

- QEMU* support
 - Integration with BlueZ on the Linux* host
 - HCI tracing
 - ► GDB
- Real devices
 - Bluetooth Monitor Protocol over console UART
 - Interleaved log messages & HCI data
 - Decoded using btmon from BlueZ
- Follow-up presentation coming about Zephyr OS-BlueZ joint usage



LE Controller implementation

- Contributed by Nordic Semiconductor
- On its way to Zephyr 1.6
- LE Link Layer
- As many instances of connected LE roles as RAM & configuration permit
- nRF5x radios supported
- Ongoing radio abstraction work
- HCI for internal interface with host



Possible configuration options

Controller-only **UART/SPI/USB Raw HCI API** Controller

Host-only

Bluetooth app

Host stack

HCI Driver

Combined Host & Controller

Bluetooth app

Host stack

Controller

Possible configuration options - details

Controller-only Host-only

- Raw HCI API
 - UART, USB, SPI
- Arduino 101* (nRF51)
- Carbon (nRF51)

- Bluetooth API
- HCI transport driver
 - UART, SPI
- Arduino 101 (Quark SE)
- Carbon (Cortex M4)
- QEMU*

Combined Host & Controller

Zephyr

- Bluetooth API
- Virtual HCI driver
- nRF52-based boards



Bluetooth BR/EDR support

- Bluetooth Classic
- ► GAP, L2CAP, RFCOMM, SDP
- Hands-Free Profile (HFP)
- Advanced Audio Distribution Profile (A2DP)
- Audio/Video Remote Control Profile



Future

- Work on upcoming specifications
- Bluetooth 5.0
- Bluetooth Mesh
- LE Link Layer support for more radios
- Better net_buf integration for Link Layer
- Link Layer Privacy



Questions?