Why we need eco-system specially for embedded Linux?
What we are doing for Renesas R-Car Linux development
embedded Linux eco-system
conclusion

# Creating Eco-System for R-Car LCB How to develop BSP for SoC and what we did

Hisao Munakata

AGL advisory board member @ Linux Foundation

March 25th 2015

# Why we need eco-system specially for embedded Linux?

C variant vs. embedd

hy we need eco-system for embedded Linux

#### Who am I?

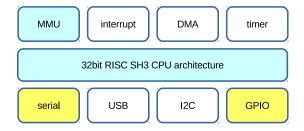
- From embedded SoC provider company Renesas
- Responsible for OSS software development and delivery for R-Car series SoC
- Working with W/W car OEM and 1st tear IVI customers
- Linux Foundation CE¹ working Gr. Steering committee member, LF/CEWG Architecture Gr. co-chair
- One of LF/CEWG LTSI<sup>2</sup> project initial proposer
- At my company, I had been encouraging my team developers to send a patches upstream

<sup>&</sup>lt;sup>1</sup>CE = consumer electronics

<sup>&</sup>lt;sup>2</sup>LTSI =Long Term Support Initiative

PC variant vs. embedded Why we need eco-system for embedded Linux

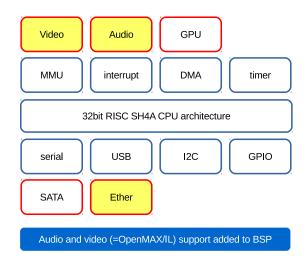
## 15 years ago, my first Linux kernel port to SH7709



C variant vs. embedde

Why we need eco-system for embedded Linux

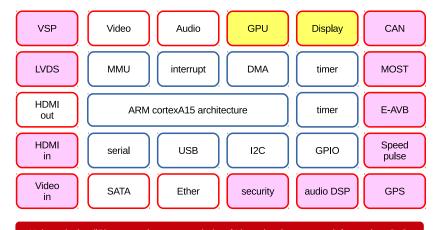
## 5 years ago, adding more peripherals for early SoC



PC variant vs. embedded

/hy we need eco-system for embedded Linux

#### Now extremely complicated drivers need integration



Unique device (IP) support becomes majority of Linux development work for modern SoC

PC variant vs. embedded

Why we need eco-system for embedded Linux

## single Linux installer can boot for all PC variant

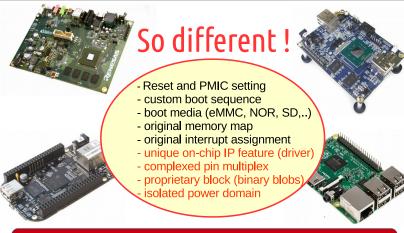


If you have a Linux distribution (like Debian) install DVD, you can boot PC, server and embedded PC with single amd64 binary image as they have commonality

PC variant vs. embedded

Why we need eco-system for embedded Linux

# embedded board requires dedicated kernel image



Every embedded boards behave differently. Your previous experience might not applied to the new SoC, boards. Also, Google can not tell you how to bring your board if that is a minor one. Emdedded Linux bring up is always painful work.

#### We need to deliver Linux BSP for embedded hardware

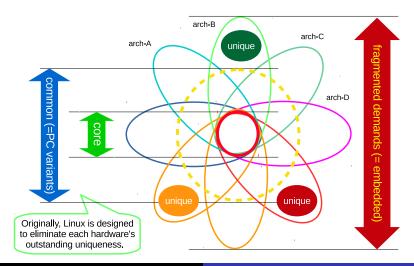
**Distribution** = verified collection of various Linux programs (=packages) per-build binary distribution = Debian, Ubuntu, Cent, Fedora source code distribution = Gentoo, Open Embedded (yocto),...

**SDK (Software Development Kit )** = subset of distribution designed for specific application = Android, Tizen IVI, MPD, Drone Code



BSP (Board Support Package ) = subset of SDK, designed for specific target hardware. Embedded SoC vendor develops BSP for their reference platform. Product producer modify BSP to fit with product hw

#### Battles between PC variant and embedded



## example (window system): X11 vs. Wayland

#### design policy comparison (GPU optimization point)

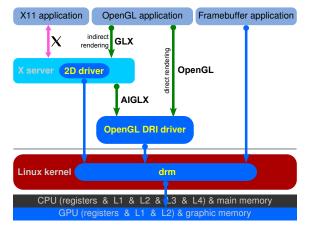
#### X11 = conservative

- sustainable solid API
- drawing is fully managed by X11 server side
- composition (=window manager) is out of X11 server and it cases bunch of IPC (=overhead)
- display surface allocated by X11 server side

#### Wayland = aggressive

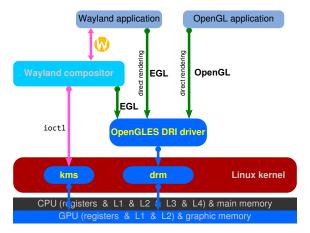
- fully utilize GPU capability
- client(=apps.) can draw directly via DRI
- composition can be integrated to Wayland server and it makes drawing simple
- client reserver surface and send pointer

## example (window system): X11 vs. Wayland



"Linux graphics drivers DRI current" by Shmuel Csaba Otto Traian. Licensed under CC BY-SA 3.0 via Wikimedia Commons - http://commons.wikimedia.org/wiki/File:Linux\_graphics\_drivers\_DRI\_current.svg#/media/File:Linux\_graphics\_drivers\_DRI\_current.svg

## example (window system): X11 vs. Wayland



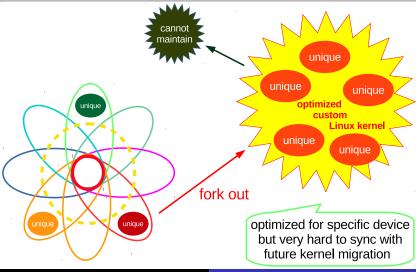
"Linux graphics drivers DRI Wayland" by Shmuel Csaba Otto Traian. Licensed under CC BY-SA 3.0 via Wikimedia Commons - http://commons.wikimedia.org/wiki/File:Linux\_graphics\_drivers\_DRI\_Wayland.svg#/media/File:Linux\_graphics\_drivers\_DRI\_Wayland.svg

#### DRI drivers contains GPU code

munakata@muna-E450: /source/linux\$ ls -l /usr/include/libdrm total 292

```
munakata munakata
                                     4096
                                                       14.31
drwxr-xr-x 2
                                              Feb
drwxr-xr-x 67
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```

#### Easy solution: fork to create original kernel, but...



PC variant vs. embedded

Why we need eco-system for embedded Linux

## Linux eco-system = the power of collective wisdom

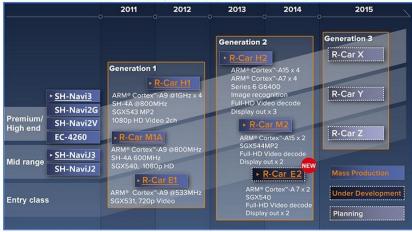


To share embedded Linux experience, eco-system driven by the cheap board is the key

# What we are doing for Renesas R-Car Linux development

#### Renesas R-Car series SoC: scalable design concept

\* "R-Car" is the nickname for Renesas' lineup of system-on-chips (SoCs) for car information systems.



http://www.renesas.com/applications/automotive/cis/cis\_highend/index.jsp

R-Car SoC intro R-Car Linux BSP development

#### BSP is source level compatible for H2,M2 and E2

#### R-Car F2

- A7 x2
- PowerVR SGX540
- 2 display support

#### R-Car M2

- A15 x2
- PowerVR SGX544MP2
- 2 display support

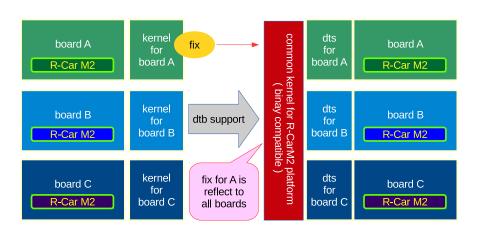
#### R-Car H2

- A15 x4 + CA7 x4
- PowerVR G6400
- 3 display support

R-Car gen2 Linux BSP support E2, M2 and H2 with same code

R-Car gen2 devices are feature and performance scalable design, we develop single Linux BSP can support all variant so that customer can use same code for all.

## kernel is binary level compatible across the boards



# Renesas R-CarM2 SOC (for mid-range system) 1/3

Item	Specification		
Product number	R8A7791		
Power supply voltage	3.3/1.8 V (IO), 1.5/1.35 V (DDR3), 1.03 V (Core)		
CPU core	ARM®Cortex™-A15	SH-4A core	
	Dual	(device option)	
Maximum operating	1.5 GHz	780 MHz	
frequency			
Processing performance	10500 DMIPS	1720 DMIPS	
Cache memory	L1 Instruction cache:	Instruction cache:	
	32 KB	32 KB	
	L1 Operand cache:	Operand cache:	
	32 KB	32 KB	
	L2 Cache:		
	2 MB		
External memory	DDR3-SDRAM		
	Maximum operating frequency: 800 MHz		
	Data bus width: 32 bits × 2 ch (6.4 GB/s × 2)		
Expansion bus	Flash ROM and SRAM,		
	Data bus width: 8 or 16 bits		
	PCI Express2.0 (1 lane)		
Graphics	PowerVR SGX 544MP2 (3D)		
	Renesas graphics processor (2D)		

http://www.renesas.com/press/news/2013/news20130926\_s.jsp

## Renesas R-CarM2 SOC (for mid-range system) 2/3

Video	Display Out × 2 ch (1 ch: LVDS, 1 ch: RGB888)
	Video Input × 3 ch
	Video codec module (H.264/AVC, MPEG-2/4, VC-1)
	IP conversion module
	JPEG accelerator
	TS Interface × 1 ch
	Video image processing (color conversion, image expansion, reduction, filter processing)
	Distortion compensation module (image renderer) × 1 ch
Audio	Audio DSP
	Sampling rate converter × 10 ch
	Serial sound interface × 10 ch
	MOST DTCP
Storage Interface	USB 3.0 host interface × 1 port (wPHY)
	USB 2.0 host interface × 2 ports (wPHY)
	SD host interface × 3 ch (SDXC, UHS-I)
	Multimedia card interface × 1 ch
	Serial ATA interface × 2 ch
In-car network and automotive peripherals	Media local bus (MLB) Interface × 1 ch (6-pin / 3-pin interface selectable)
	CAN Interface × 2 ch
	IEBus™ Interface
	GPS baseband module (Galileo, GLONASS) (device option)
	Ethernet controller AVB (IEEE802.1BA, 802.1AS, 802.1Qav and IEEE1722, GMII/MII, without PHY)

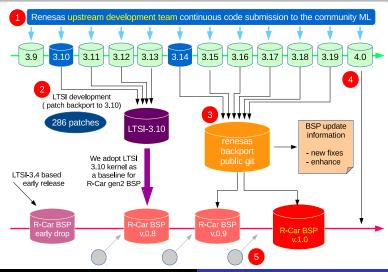
http://www.renesas.com/press/news/2013/news20130926\_s.jsp

## Renesas R-CarM2 SOC (for mid-range system) 3/3

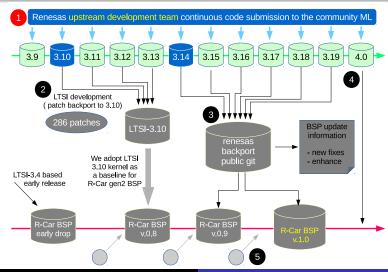
Security	Crypto engine (AES, DES, Hash, RSA)
	Secure RAM
Other peripherals	DMA controller
	LBSC DMAC: 3 ch / SYS-DMAC: 30 ch / RT-DMAC: 3 ch /
	Audio-DMAC: 26 ch / Audio (peripheral)-DMAC: 29 ch
	32 bit timer × 12 ch
	PWM timer × 7 ch
	I <sup>2</sup> C bus interface × 9 ch
	Serial communication interface (SCIF) × 18 ch
	Quad serial peripheral interface (QSPI) × 1 ch (for boot)
	Clock-synchronized serial interface (MSIOF) × 3 ch (SPI/IIS)
	Ethernet AVB controller (IEEE802.1BA/802.1AS/802.1Qav/IEEE1722, GMII/MII, without PHY)
	Ethernet controller (IEEE802.3u, RMII, without PHY)
	Interrupt controller (INTC)
	Clock generator (CPG) with built-in PLL
	On-chip debugger interface
Low power mode	Dynamic Power Shutdown (CPU core, 3D, IMP)
	AVS and DVFS function
	DDR-SDRAM power supply backup mode
Package	831-pin Flip Chip BGA (27 mm × 27 mm)

http://www.renesas.com/press/news/2013/news20130926\_s.jsp

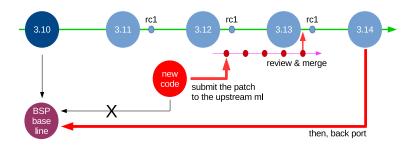
## R-Car gen2 Linux BSP whole development process



# (1) Upstream If\_pub\_whowriteslinux2015.pdf

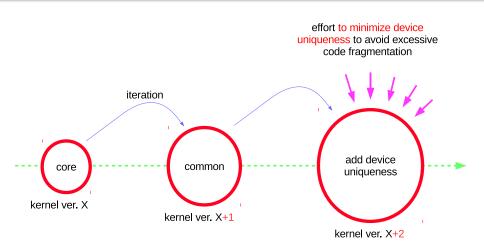


## Renesas adopts upstream first strategy



pros	cons
- clean code (reviewed by the community) - coordinated with existing code - merged to the upstream code - no need to keep in-house code	take time (roughly 6 month)     might need iterative approach (bit b bit)     might need code adjustment

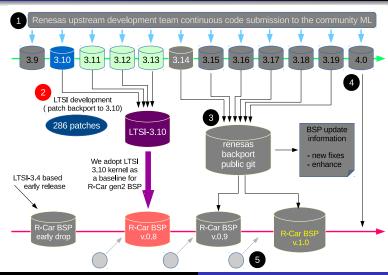
## iterative approach to minimize code fragmentation



# Result of 2014 If\_pub\_whowriteslinux2015.pdf



## (2) LTSI development process



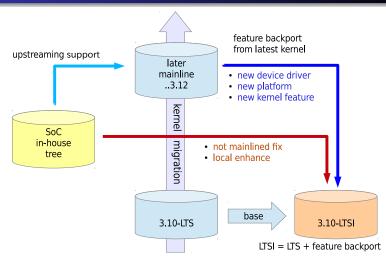
## (2) LTSI = cutting edge device on the solid software

version	fixes
v3.3 -> v3.3.8	698
v3.4 -> v3.4.95	4,506
v3.5 -> v3.5.7	816
v3.6 -> v3.6.9	676
v3.7 -> v3.7.10	718
v3.8 -> v3.8.13	996
v3.9 -> v3.9.11	746
v3.10 -> v3.10.69	4,175
v3.11 -> v3.11.10	677
v3.12 -> v3.12.38	4,262
v3.13 -> v3.13.11	903
v3.14 -> v3.14.33	2,786
v3.15 -> v3.15.10	703
v3.16 -> v3.16.7	871

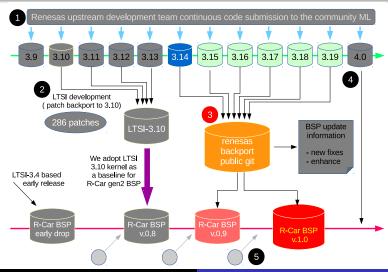


R-CarM2 was released after the release of kernel 3.10

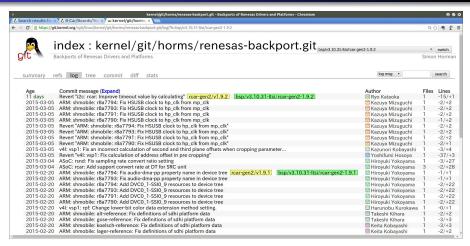
## Backported R-carM2 device support to LTSI-3.10



# (3) continuous backport after LTSI merge closed

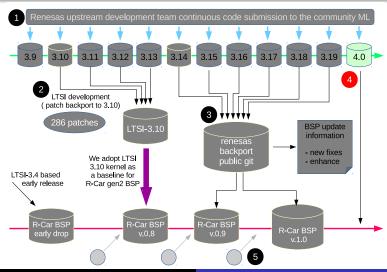


# (3) continuous backport after LTSI merge closed



 $\label{limits} $$ $$ $ https://git.kernel.org/cgit/linux/kernel/git/horms/renesas-backport.git/log/?h=bsp/v3.10.31-ltsi/rcar-gen2-1.9.2 $$$ 

# (4) super-long term security fix adoption



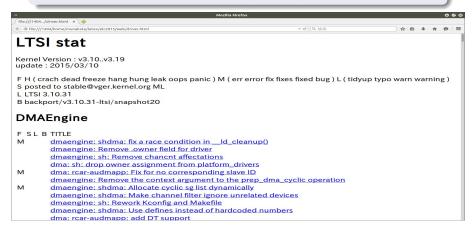
## BSP maintenance: new bug-fix patch tracking

#### We continue check if new fixes is available

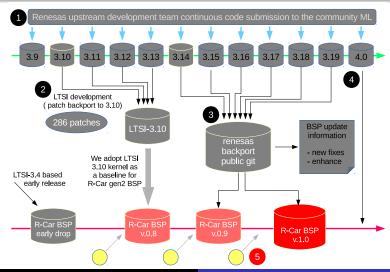
- automated upstream patch scan from git
- crawling scope is own code or modified code
- F: patch severity parsing
  - H: crash, dead, freeze, hang, hung, leak, oops, panic
  - M : err, error, fix, fixes, fixed, bug
  - L: tidyup, typo, warn, warning
- S :check if this patch is cc'd to stable@vger.kernel.org
- L :check if this patch is already a part of LTSI kernel
- B :check if this patch is send to renesas-backport git

# BSP maintenance : new bug-fix patch tracking

actual scan result example (comparing upstream 3.10..3.19)



## (5) local in-house patch adoption and elimination



# (5) local in-house patch adoption and elimination

#### we try to eliminate in-house code from our BSP, however

- Due to time constraint (=up to six months needed for upstream-first attempt), we still need to manage some in-house patch.
- We start up-porting challenge (in-house code to the upstream flow) to eliminate (at least reduce) in-house code.
- It requires an extra code polish to comply with latest mainline kernel patch adoption criteria. But we believe this is the valuable challenges.

Openness (hard & soft) is a key

# embedded Linux eco-system

#### R-Car low-cost reference board intro. @ eLinux wiki

#### Hardware Pages

The following hardware pages have LOTS of information on this site:



BeagleBoard











MIPS Creator CI20





Ranana Pi











Renesas R-Car SILK









http://elinux.org/R-Car/Boards/Porter

#### Renesas R-CarM2 Porter board on eLinux

#### R-Car/Boards/Porter

+12V in

< R-Car
Introduction

#### Contents [hide] 1 Introduction 2 Hardware 3 Hardware Features 4 Where to how 5 R-Car M2 SoC Documentation 6 Official Porter board documentation 7 Quick Start How To 7.1 Build Yocto image 7.2 Connect 12 V power supply to the board 7.3 Connect to serial console 7.3.1 picocom 7.3.2 minicom 7.4 Power on the board and go to U-Boot prompt 7.5 Configure U-Boot to boot over TFTP + NFS or from a micro SD card 8 Bootloader 8.1 Updating U-Boot 8.2 Updating QSPI Loader 9 FAQ 9.1 How do I change/update MAC address for Ethernet interface? 9.2 How do I connect an external LVDS display with touchscreen support? 9.3 Which operating systems/distributions can be used with R-Car M2 Porter board?

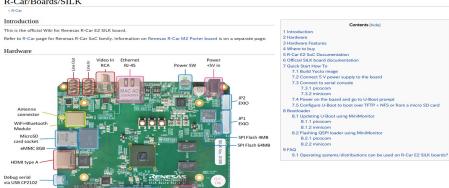
http://elinux.org/R-Car/Boards/Porter

Debug serial

9.4 Known Issues

#### Renesas R-CarE2 SILK board on eLinux

#### R-Car/Boards/SILK



http://elinux.org/R-Car/Boards/SILK

JTAG

VGA

Dual USB 2.0

#### Renesas R-CarM2/E2 yocto instruction on eLinux

#### R-Car/Boards/Yocto

< R-Car

This page contains information on building and running Yocto on Renesas R-Car E2 SILK and Renesas R-Car M2 Porter boards.

#### Yocto versions

Poky-1.6.1 is supported. Specific commit of meta-openembedded is required.

#### Preliminary steps

- Download proprietary graphics and multimedia drivers from Renesas. Evaluation version is available at http://www.renesas.com/secret/r\_car\_download/rcar\_demoboard.jsp@ Graphic drivers are required for X11 and Wavland. Multimedia drivers are optional.
- 2. Install required packages

#### Ubuntu and Debian

sudo apt-get install gawk wget git-core diffstat unzip texinfo gcc-multilib ¥
build-essential chroath socat libsd11.2-dev xterm

#### Contents [hide]

#### 1 Yocto versions 2 Preliminary steps

- 2.1 Ubuntu and Debian
- 2.2 Fedora
  3 Building the BSP for Renesas R-Car SILK and Porter
- 4 Running Yocto image
  - 4.1 Loading kernel via TFTP and rootfs via NFS 4.1.1 Ubuntu
    - 4.1.1 Ubuntu 4.1.2 Fedora
    - 4.1.2 Fedora
    - 4.1.3 Ubuntu
    - 4.1.4 Fedora 4.1.5 Debian/Ubuntu
    - 4.1.5 Debian/Ubuntu 4.1.6 Fedora
    - 4.1.6.1 For SILK board
    - 4.1.6.2 For Porter board
- 4.2 Loading kernel and rootfs from microSD card 5 Known issues and limitations

#### Fedora

sudo yum install gawk make wget tar bzip2 gzip python unzip perl patch ¥ diffutils diffstat git cpp gcc gcc-c++ glibc-devel texinfo chrpath ¥ ccache perl-Data-Dumper perl-Text-ParseWords perl-Thread-Queue socat ¥ SDL-devel xterm

Refer to Yocto Project Quick Start for more information.

#### Building the BSP for Renesas R-Car SILK and Porter 1. Create a directory and switch to it

Warning! Yocto builds require a lot of disk space (up to 100 GB). Make sure you have got enough before starting the build.

http://elinux.org/R-Car/Boards/Yocto

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# conclusion

#### Conclusion

- Introduced why embedded Linux requires BSP and what is the potential problem of too unique embedded feature adoption to the Linux kernel.
- Introduced Renesas R-Car gen2 Linux BSP development process and result.
- Introduced newly opened public web (eLinux) where you can obtain R-Car Linux BSP and related information.

#### Resources

- R-CarH2 intro = http://am.renesas.com/applications/automotive/cis/cis\_highend/rcar\_h2/index.jsp
- R-CarM2 intro =
  http://am.renesas.com/applications/automotive/cis/cis\_highend/rcar\_m2/
- R-CarE2 intro = http://am.renesas.com/applications/automotive/cis/cis\_highend/rcar\_e2/index.jsp
- R-Car series road map = http://www.renesas.eu/products/soc/assp/automotive/index.jsp
- R-CarM2 Porter board = http://elinux.org/R-Car/Boards/Porter
- R-CarE2 SILK board = http://elinux.org/R-Car/Boards/SILK
- R-Car gen2 public yocto intro = http://elinux.org/R-Car/Boards/Yocto
- R-Car gen2 GFX/MMF evaluation download = http://www.renesas.com/secret/r\_car\_download/rcar\_demoboard.jsp
- e-mail = Hisao Munakata (hisao.munakata.vt(at)renesas.com)